



*Beam Instrumentation Department*

# **DC Current Transformer (DCCT)**

Calibration Talk

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July 14, 2004

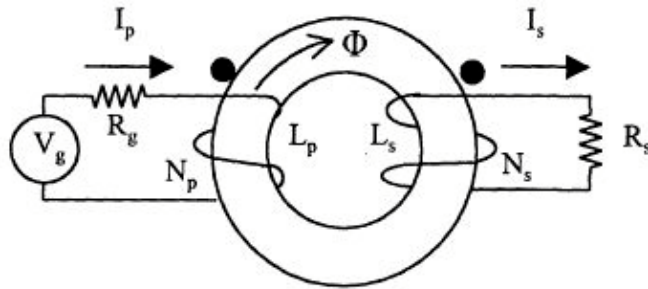


# Introduction

- Beam monitors are designed to sense the electric field, magnetic field, or some combination.
- Beam current monitors are generally devices that interact with the beam's magnetic field to measure beam current, charge, and/or pulse shape.
- Beam current monitors are based on transformer circuit theory.



# Basics of Classical Transformer



$$\Phi_k = \frac{L_k \cdot i_k}{N_k}$$

$$\Phi_T = \frac{L_p \cdot i_p}{N_p} - \frac{L_s \cdot i_s}{N_s}$$

$$i_s = \frac{s \cdot \Phi_T \cdot N_s}{R_e}$$

$$V_g = i_p \cdot R_g + s \cdot \Phi_T \cdot N_p$$

- Current in any  $N$  turn winding  $k$  produces a magnetic flux in the core.
- The voltage appearing across each winding is proportional to the time rate change of the total flux.
- In the beam current model, the voltage generator is replaced by a current generator.
- For  $R_{\text{beam}} \gg R_s$ , the secondary current is very close to  $1/N_s$  times the beam current.



# DCCT Intensity Monitor System

- The pickup consists of 2 sets of cores, which are excited in opposite senses with the beam signal acting as the primary turn.
- Placing these toroidal transformers in the feedback loop creates an active current transformer, extending the system's useful bandwidth.
- Any magnetic flux change in the active beam transformer core is handled with the addition of a magnetic modulator and control loop.
  - A particle beam in the aperture of the toroids will introduce asymmetry and give an output of even harmonics at the modulation frequency. The 2<sup>nd</sup> harmonic component of the output signal is proportional to the primary current and its phase is determined by the direction of the beam.
  - A synchronous demodulator detects this 2<sup>nd</sup> harmonic signal synchronous with input.
  - Using that signal in a closed feedback loop, a feedback current is produced to null out the magnetic imbalance – maintaining 0-average flux.
  - A stable, precision resistor in the feedback path yields a voltage output.

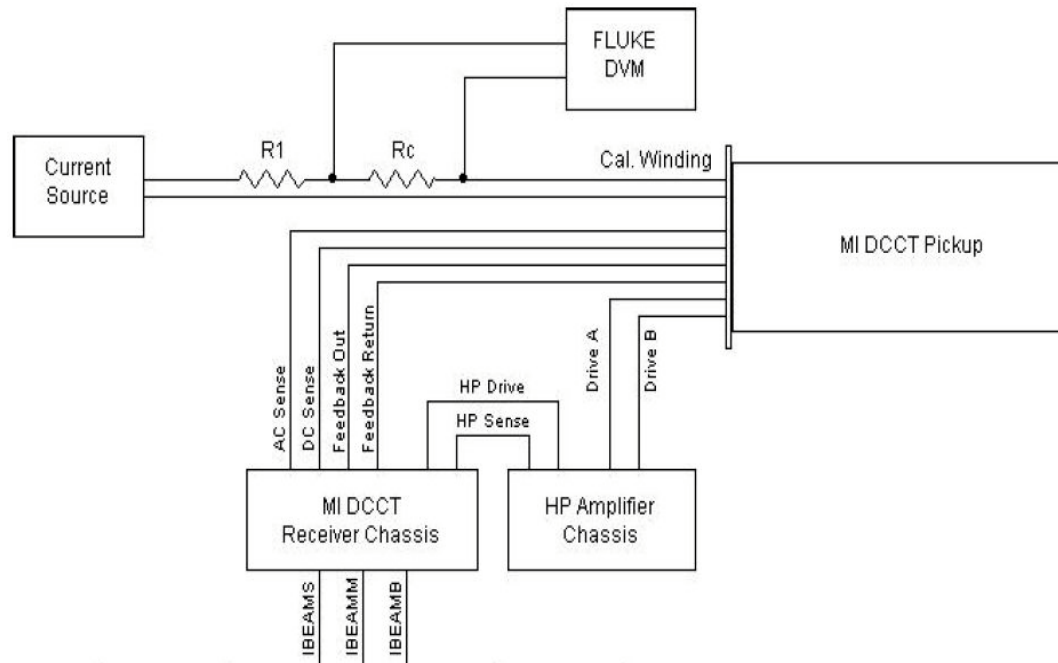


## DCCT Output Signals

- DCCT Receiver has 3 different buffered outputs to provide more useful scaling: The “S” is for small intensities, “M” for medium, and “B” for big.
- The “B” output is simply a buffered output of the signal received.
- “M” output has amplification and a low-pass filter. (e.g. 500 Hz anti-aliasing LP Filter for MI DCCT).
- “S” output has additional notch filtering to remove parasitic resonant 1<sup>st</sup> and 3<sup>rd</sup> harmonic frequency components (e.g. 200 Hz & 600Hz Filter for MI DCCT). It also has gain.
- “B” is used to provide inputs to digitizing front-end. As a result, a intermediate filter module is used to mimic filtering schemes in “M” and “S”. This allows the digitizing front-end to keep similar responses the old MADC readings over the full range of beam intensities.



# MI DCCT Calibration Test Setup



- Current source is typically a precision voltage supply.
- Known DC currents are sent through calibration winding of detector.
- Test currents are determined by measuring voltage drop across calibration resistor as current source is stepped from 0 to full-scale.
- ACNET readings are compared to calculated intensities for a given current range under test.
- Calibration setups for other DCCTs (e.g. RR, TEV, PBAR) are similar.



## Example of DCCT Calibration Calculations

<b>Electron Charge =</b>			1.60E-19						
<b>RFFrequency (8Gev/150Gev) =</b>			52958000						
<b>Burden Resistor (Ohms) =</b>			10.12						
			<b>I:BEAM</b>						
			35.531716	<<--max	Calculated from I:BEAM readings				
<b>VIN</b>	<b>Amps</b>	<b>Watts</b>	<b>Calculated</b>	<b>ACNET Measured</b>	<b>Voltage Reading</b>	<b>LSF CORRECTED (E12)</b>	<b>Errors With Correction</b>		
0.000	0.000	0.000	0.000	0.142	0.036	-0.047	0.047		
0.832	0.082	0.068	5.694	5.180	1.383	5.656	0.038		
1.537	0.152	0.233	10.522	9.490	2.536	10.534	-0.012		
2.167	0.214	0.464	14.841	13.360	3.571	14.914	-0.073		
2.873	0.284	0.816	19.675	17.610	4.707	19.724	-0.049		
3.547	0.350	1.243	24.289	21.670	5.793	24.320	-0.031		
4.275	0.422	1.806	29.275	26.040	6.961	29.266	0.009		
5.003	0.494	2.473	34.261	30.390	8.124	34.189	0.071		
			<b>GAIN</b>	<b>OFFSET</b>					
<i>Isf</i>			0.883525448	0.183094923				<b><math>\Sigma Errors</math></b>	0.000
<i>Old</i>			3.74	0.006				<b><math>\chi^2 (E12)</math></b>	0.018
<b>New</b>			4.233041629	-0.200441224				<b><math>RMS / \sigma (E12)</math></b>	0.054
			<b>I:BEAM</b>						
			<b>%<math>\Delta</math> in Gain</b>	13%					
			<b><math>\Delta</math> in Offset</b>	-0.21					